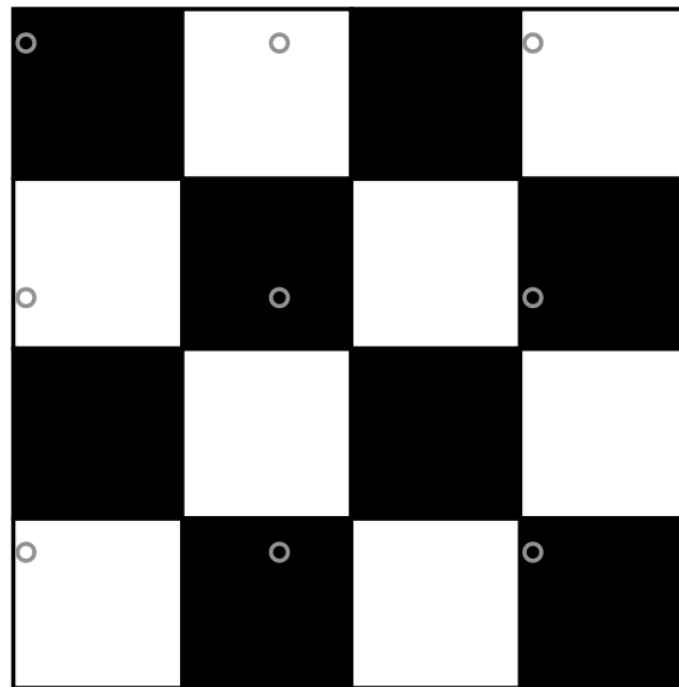
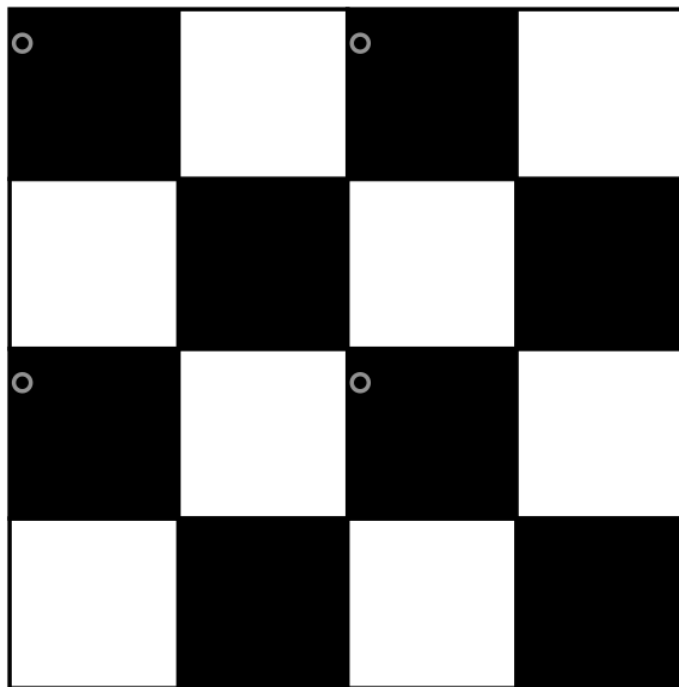
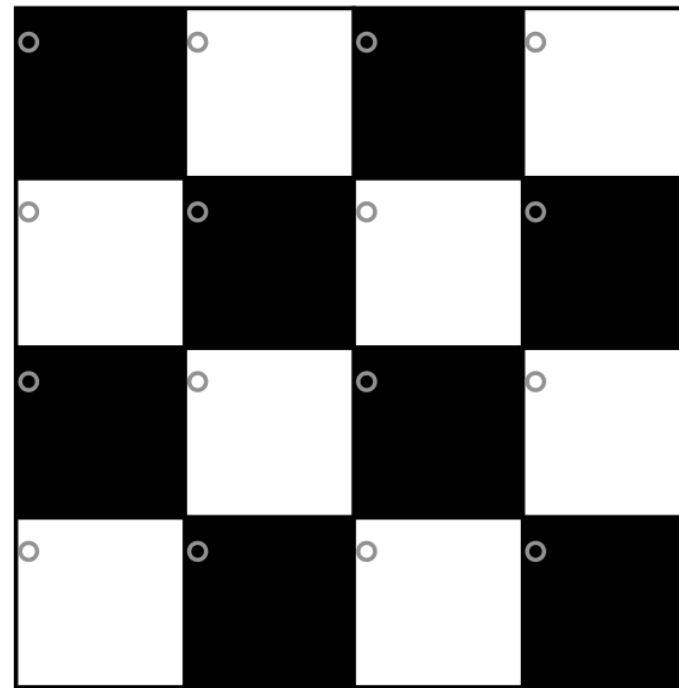
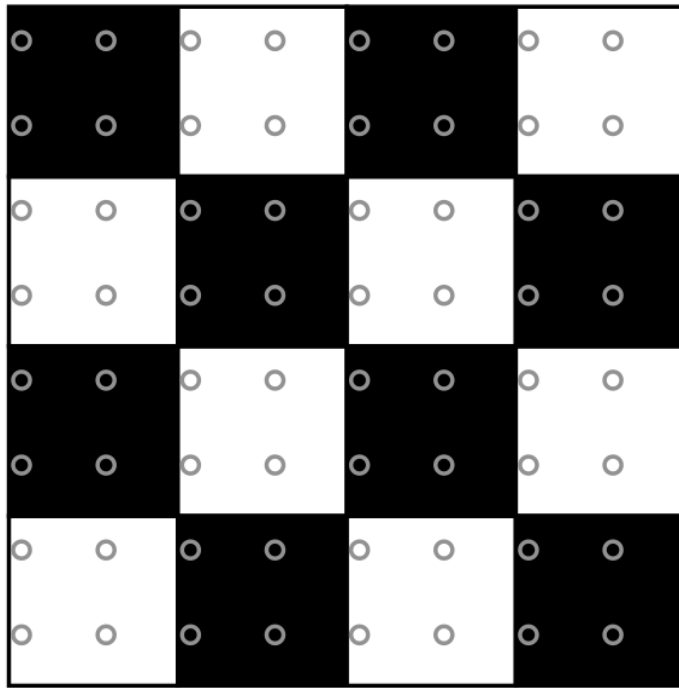


Transformácie





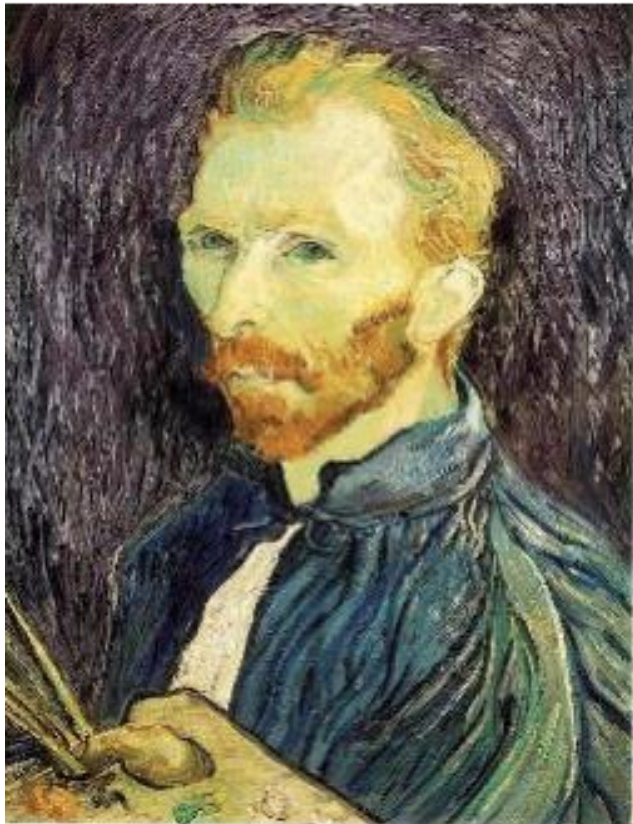
Nyquist–Shannon sampling theorem

If a function $x(t)$
contains no **frequencies** higher than **B hertz**,
it is completely determined
by giving its ordinates at a **series of points**
spaced **$1/(2B)$ seconds** apart.

Aliasing
Moiré pattern

Fourierová transformácia

Redukovanie počtu pixelov



1/2



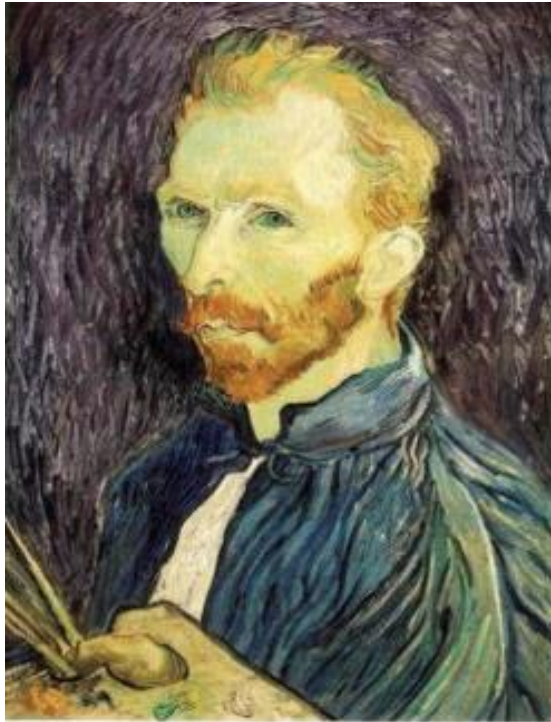
1/4 (2x zoom)



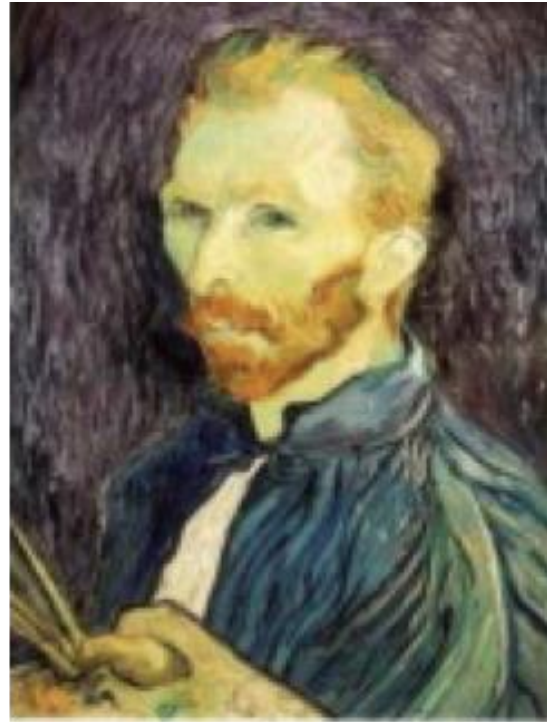
1/8 (4x zoom)

Decimation

- Aplikovanie low-pass filtra



Gaussian 1/2

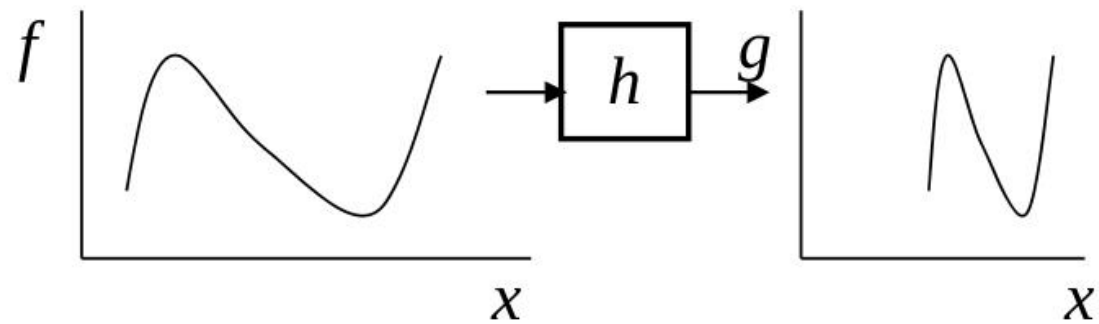
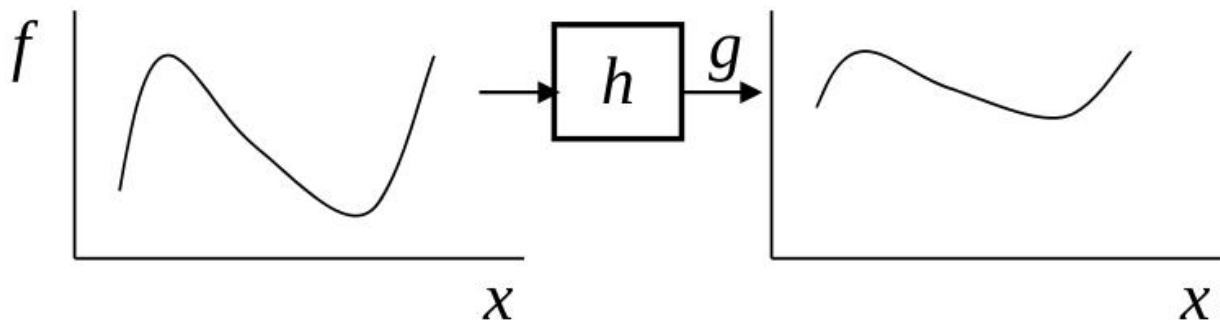
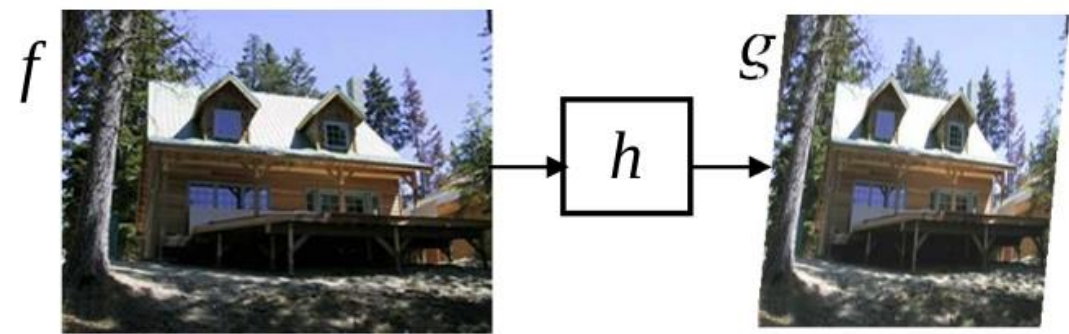
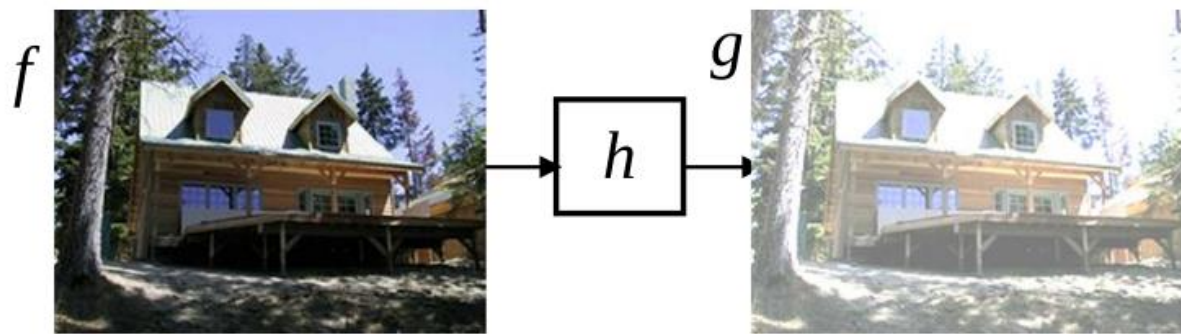


G 1/4



G 1/8

Geometrické transformácie



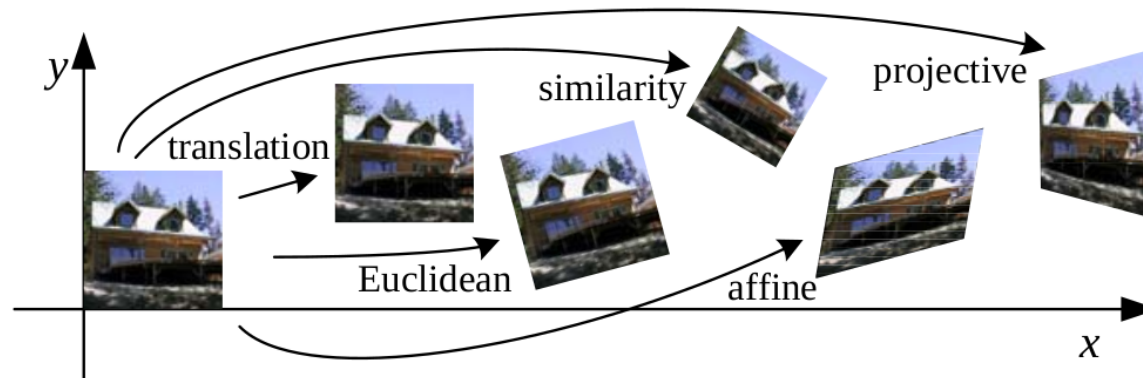
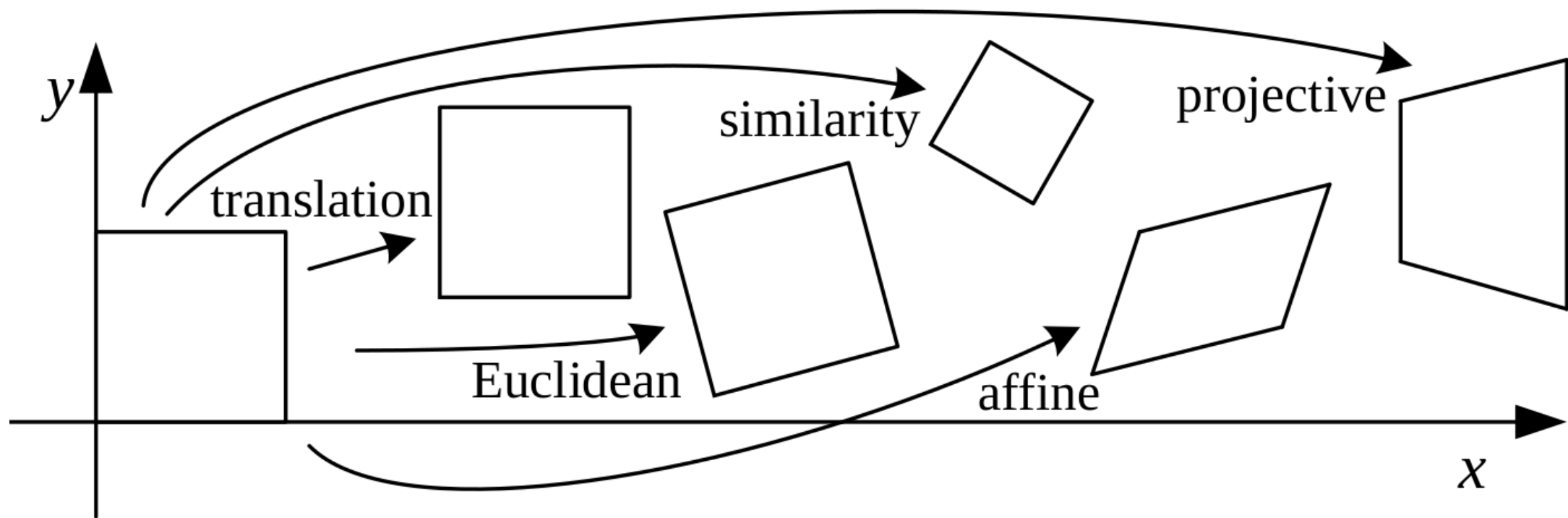


Figure 3.44 *Basic set of 2D geometric image transformations.*

Transformation	Matrix	# DoF	Preserves	Icon
translation	$\begin{bmatrix} \mathbf{I} & \mathbf{t} \end{bmatrix}_{2 \times 3}$	2	orientation	
rigid (Euclidean)	$\begin{bmatrix} \mathbf{R} & \mathbf{t} \end{bmatrix}_{2 \times 3}$	3	lengths	
similarity	$\begin{bmatrix} s\mathbf{R} & \mathbf{t} \end{bmatrix}_{2 \times 3}$	4	angles	
affine	$\begin{bmatrix} \mathbf{A} \end{bmatrix}_{2 \times 3}$	6	parallelism	
projective	$\begin{bmatrix} \tilde{\mathbf{H}} \end{bmatrix}_{3 \times 3}$	8	straight lines	



Transform	Matrix	Parameters \mathbf{p}
translation	$\begin{bmatrix} 1 & 0 & t_x \\ 0 & 1 & t_y \end{bmatrix}$	(t_x, t_y)
Euclidean	$\begin{bmatrix} c_\theta & -s_\theta & t_x \\ s_\theta & c_\theta & t_y \end{bmatrix}$	(t_x, t_y, θ)
similarity	$\begin{bmatrix} 1 + a & -b & t_x \\ b & 1 + a & t_y \end{bmatrix}$	(t_x, t_y, a, b)
affine	$\begin{bmatrix} 1 + a_{00} & a_{01} & t_x \\ a_{10} & 1 + a_{11} & t_y \end{bmatrix}$	$(t_x, t_y, a_{00}, a_{01}, a_{10}, a_{11})$
projective	$\begin{bmatrix} 1 + h_{00} & h_{01} & h_{02} \\ h_{10} & 1 + h_{11} & h_{12} \\ h_{20} & h_{21} & 1 \end{bmatrix}$	$(h_{00}, h_{01}, \dots, h_{21})$