

Binárne obrazy

Matematická morfológia



Original (f)



Darken ($f - 128$)



Lighten ($f + 128$)



Invert ($255 - f$)



Low Contrast ($f/2$)



Original (f)



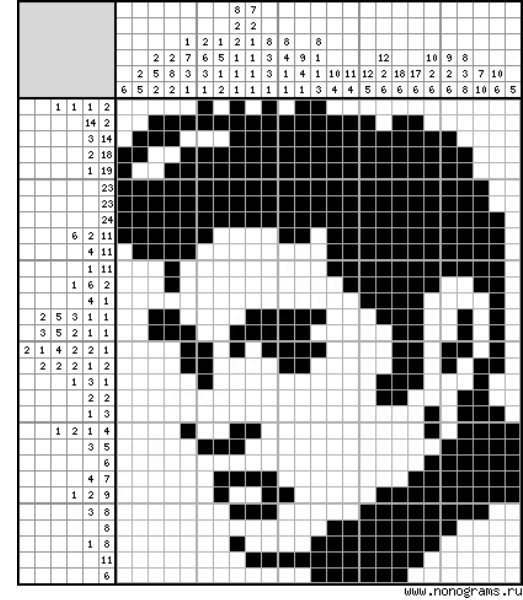
High Contrast ($f * 2$)



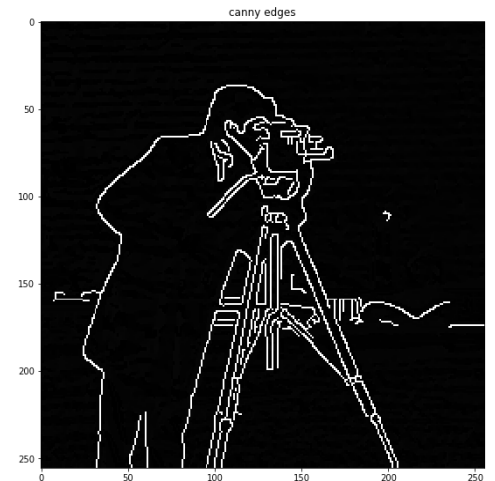
Gray ($0.3f_R + 0.6f_G + 0.1f_B$)

Binárny obraz

- 1-bitová hodnota jasů pre každý pixel
- Malá veľkosť súboru (+ run-length encoding)
- Výstup operácii - napr. detekcie hrán

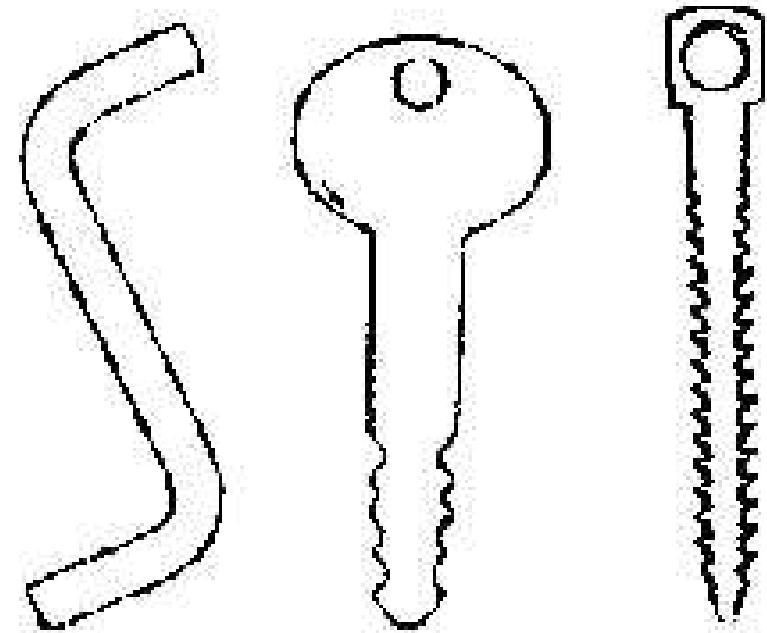


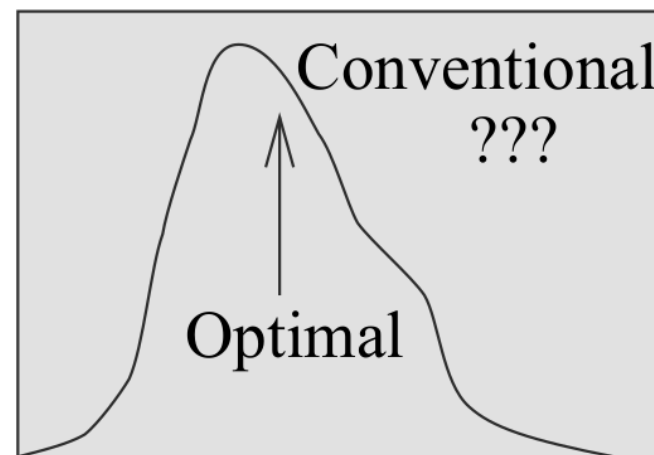
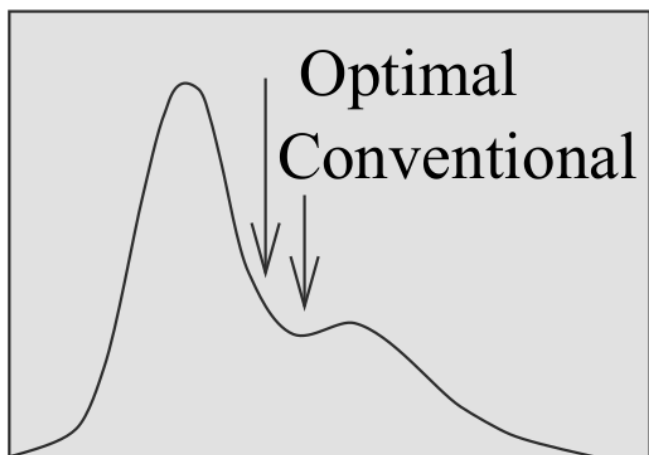
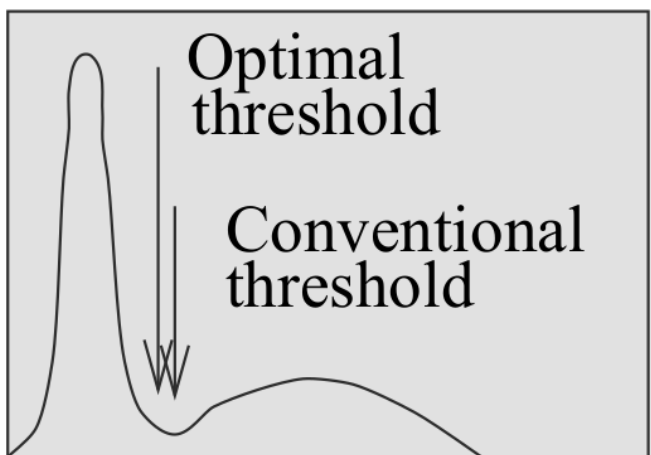
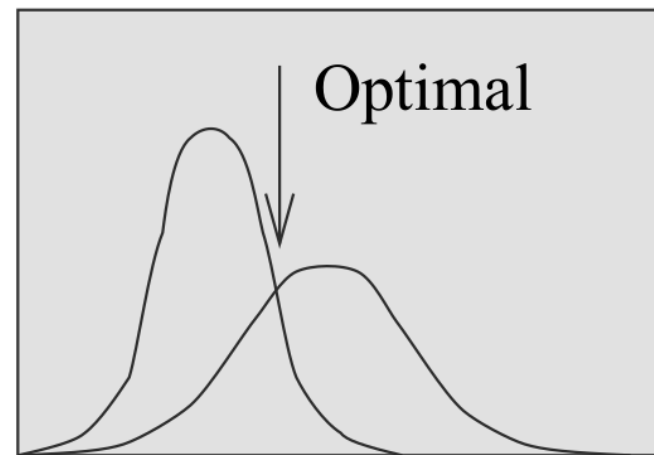
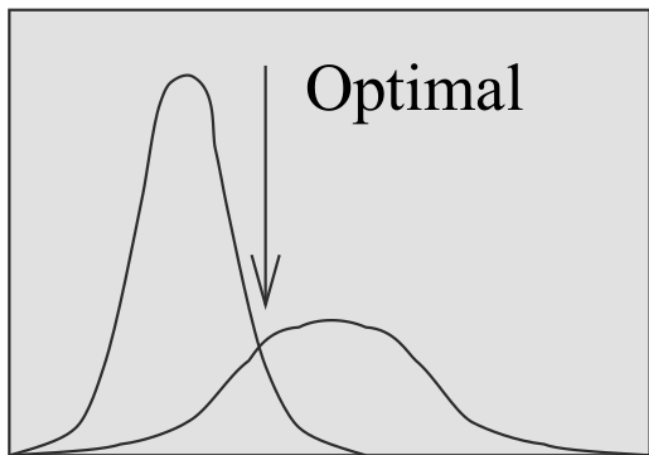
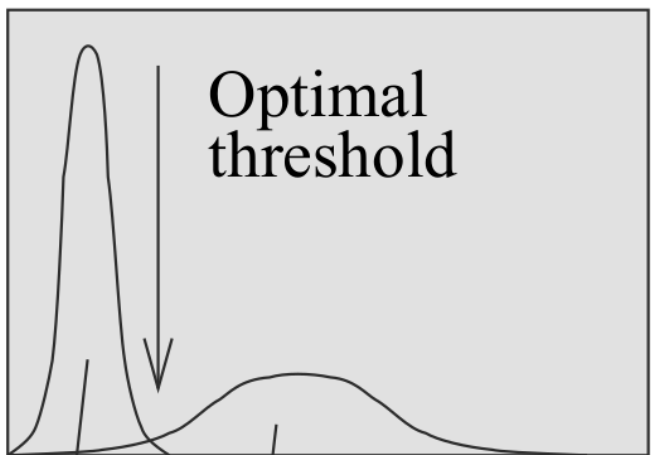
$$\theta(f, t) = \begin{cases} 1 & \text{if } f \geq t, \\ 0 & \text{else,} \end{cases}$$



Prahovanie

Prahovanie podľa úrovne jasú





Algorithm 6.2: Otsu's threshold detection

1. For an image I on G gray levels, compute the gray-level histogram $H(0), H(1), \dots, H(G - 1)$. Normalize the histogram by dividing through by the number of pixels in I —the histogram now represents the probability of each gray-level.
2. For each possible threshold $t = 0, \dots, G - 2$ partition the histogram into background B (gray-levels less than or equal to t), and foreground F (gray-levels more than t).
3. Compute $\sigma_B(t), \sigma_F(t)$, the variance of the background and foreground gray-levels. Compute the probability of a pixel being background

$$\omega_B(t) = \sum_{j=0}^t H(j)$$

and $\omega_F(t)$ similarly.

Set

$$\sigma(t) = \omega_B(t)\sigma_B(t) + \omega_F(t)\sigma_F(t)$$

and select as threshold $\hat{t} = \min_t(\sigma(t))$.

Metrika, vzdialenosť, susedstvo

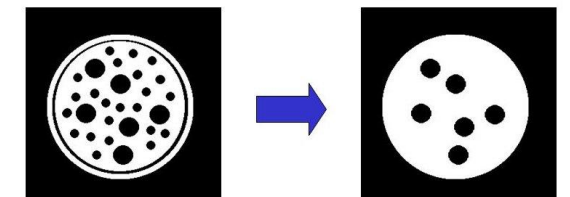
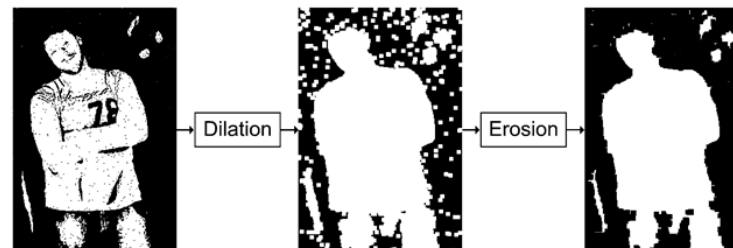
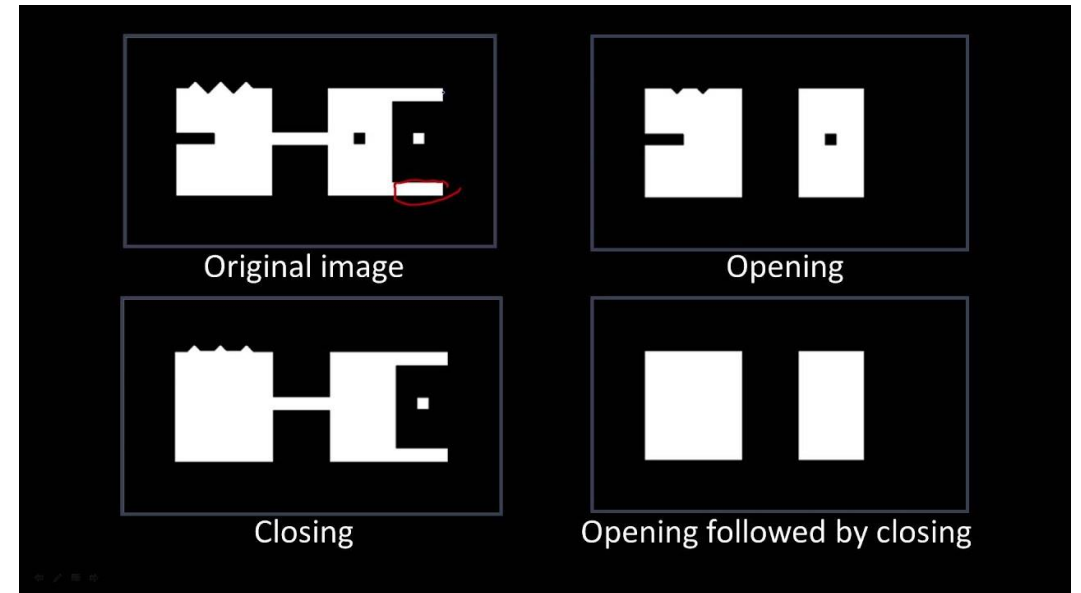
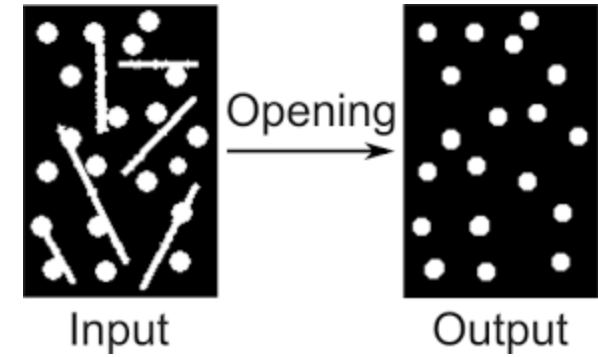
Matematická morfológia

Dilatácia a Erózia



Otvorenie a uzavretie

- Opening = erózia + dilatácia
 - Zväčší diery
 - Odstráni malé objekty
 - Oddelí objekty
- Closing = dilatácia + erózia
 - Zachová malé objekty
 - Odstráni diery
 - Spojí objekty



Morfologické operácie

- Počet jednotiek

dilation: $\text{dilate}(f, s) = \theta(c, 1)$;

erosion: $\text{erode}(f, s) = \theta(c, S)$;

majority: $\text{maj}(f, s) = \theta(c, S/2)$;

opening: $\text{open}(f, s) = \text{dilate}(\text{erode}(f, s), s)$;

closing: $\text{close}(f, s) = \text{erode}(\text{dilate}(f, s), s)$.



(a)



(b)



(c)



(d)



(e)



(f)

Distance transform

0	0	0	0	1	0	0
0	0	1	1	1	0	0
0	1	1	1	1	1	0
0	1	1	1	1	1	0
0	1	1	1	0	0	0
0	0	1	0	0	0	0
0	0	0	0	0	0	0

0	0	0	0	1	0	0
0	0	1	1	2	0	0
0	1	2	2	3	1	0
0	1	2	3			

0	0	0	0	1	0	0
0	0	1	1	2	0	0
0	1	2	2	3	1	0
0	1	2	2	1	1	0
0	1	2	1	0	0	0
0	0	1	0	0	0	0
0	0	0	0	0	0	0

0	0	0	0	1	0	0
0	0	1	1	1	0	0
0	1	2	2	2	1	0
0	1	2	2	1	1	0
0	1	2	1	0	0	0
0	0	1	0	0	0	0
0	0	0	0	0	0	0

Hit or miss

0	0	0
don't care	1	don't care
1	1	1

Structuring element

- The structuring element has pixels with 3 values
 - ➔ 0: corresponding pixel must be 0
 - ➔ 1: corresponding pixel must be 1
 - ➔ don't care

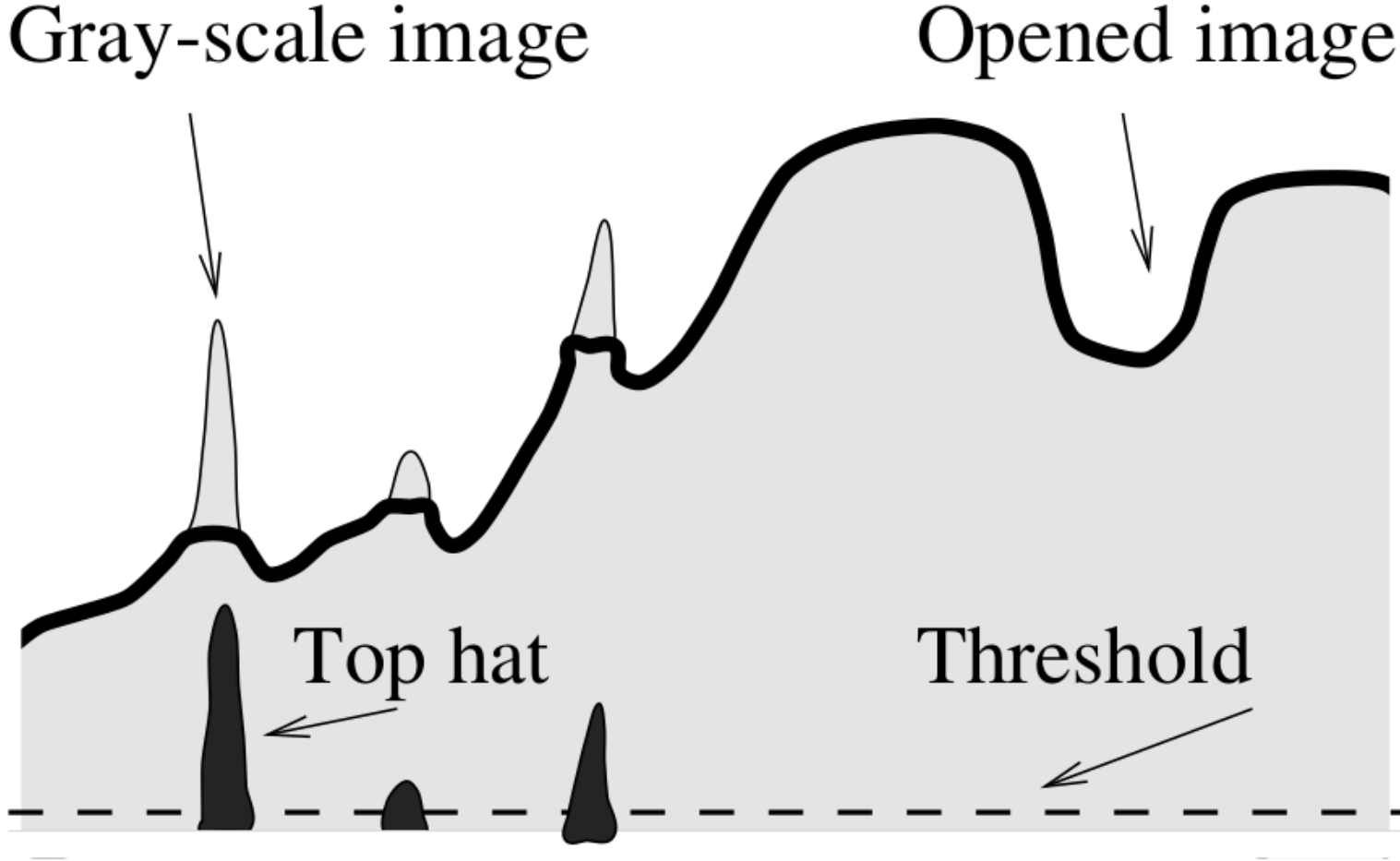
	0	0	0
	1	1	0
Input pixels	1	1	1

= true

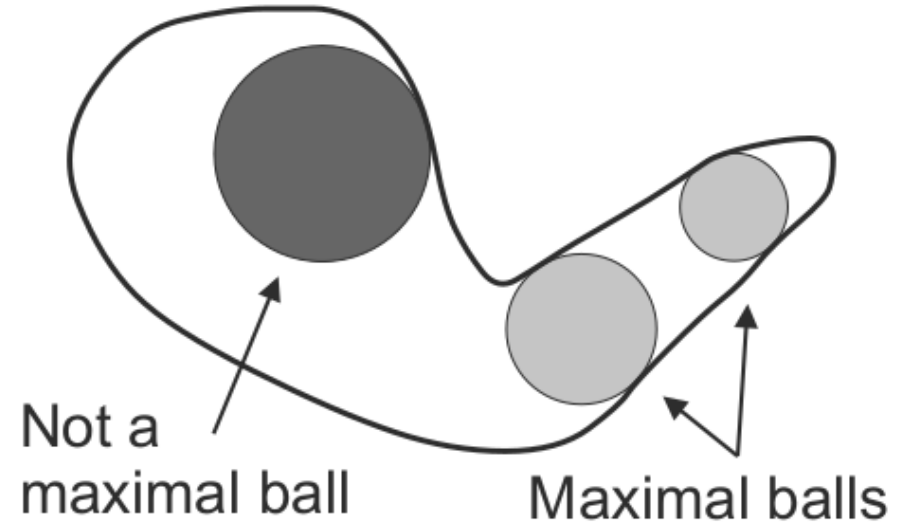
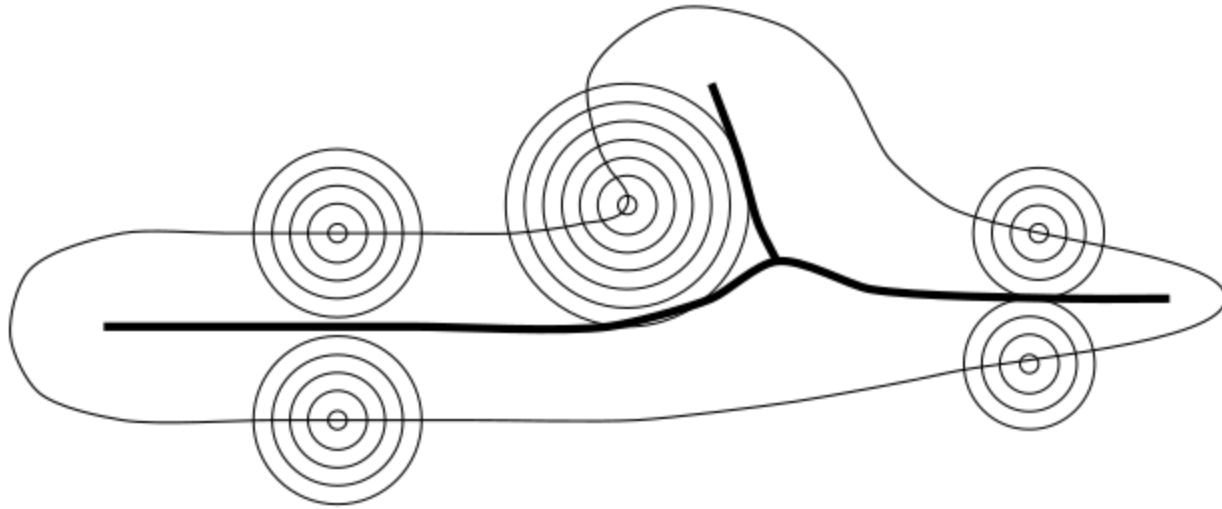
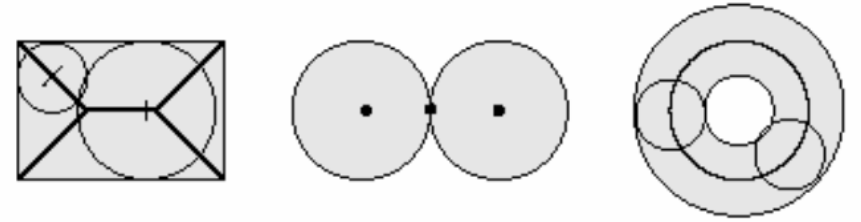
	0	0	1
	1	1	0
Input pixels	1	1	1

= false

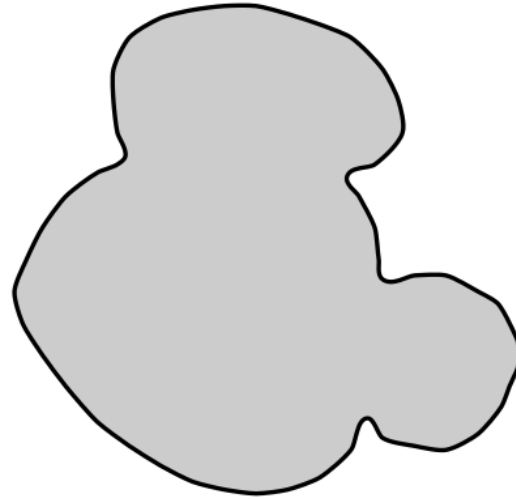
Top hat



Skeleton



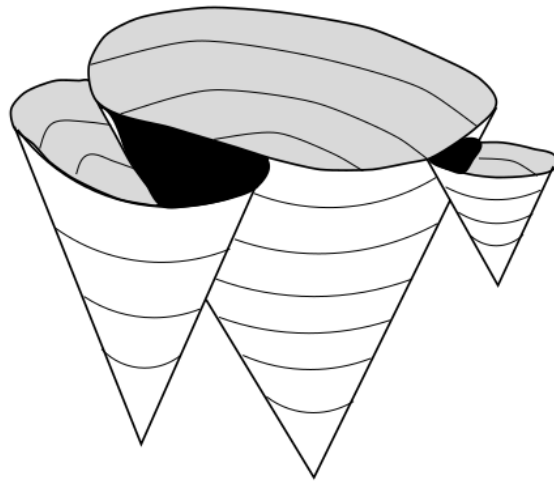
Watershed



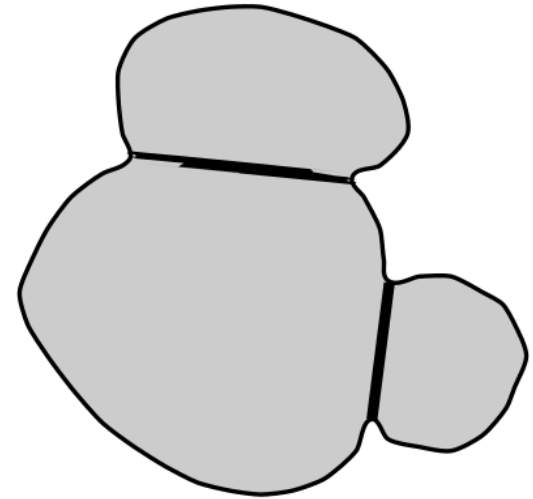
(a)



(b)



(c)



(d)

Granulometry

